

Qualcomm[®] Hexagon™ NPU

Eric Mahurin Senior Director, Technology Qualcomm Technologies, Inc

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Hexagon NPU

High Performance, Power Efficient ML Inference Processor for Qualcomm® SoCs



Hardware

Hexagon NPU

• Processor executing 3 instruction sets:

- Scalar: For control flow and general purpose
- Vector: General purpose data-parallel compute
- Tensor: Matrix multiply and convolutional layer
- Over multiple threads using shared memories (core local & cached DDR)
- DSP features:
 - VLIW, hardware looping
 - Targets DSP and compute-heavy workloads
- CPU-like features:
 - Virtual \rightarrow Physical translation, security, caching
 - Branching (call/return/indirect), exceptions, interrupts
 - Conventional software tools (including LLVM)



- Maximized efficient single-core performance
 - Make the most of resources



• Vector SIMD - like other SIMD extensions, but wider

- 1 Kb = 128B = 64H = 32W wide
- 8/16/32 bit fixed-point, 16/32 bit floating-point
- Compute and registers
 - 4 compute, 1 load, and 1 store VLIW resources
 - 32 vector registers and 4 vector predicate registers
- Memory access
 - Load/store with L2/DDR or TCM
 - Fully parallel scatter & gather with TCM to address arbitrary dataparallel workloads
- Target applications
 - Originally for image processing
 - Adapted to additional workloads including DNNs



Tensor

Tensor SIMD

- Tensor instead of vector as data-parallel quantum
- 2D matrices, 3D (X, Y, depth), and 4D (multiple 3D)
- Bit widths (activations * weights):
 - Integer: (8/16) * (4/8/16)
 - Float: FP16 * FP16
- ISA accelerates:
 - Matrix multiply
 - Convolutional layer
 - Depth-wise and other small group sized convolutions
 - Fused activation functions
 - Per output-channel scaling



Programming Model

Architecture – Threads

• Each thread has its own program

- VLIW for predictable Instruction Level Parallelism
- Scalar ISA for control flow and serial compute

• SIMD extension acquired/released

- While acquired, a program has extension capabilities
- Scalar, vector, and tensor each have dedicated registers
 - Instructions operate on thread-local registers and [potentially shared] memory



Architecture – Memory model

- Coherent memory between threads
 - Normal synchronization between threads
- Only scalar instructions uses L1 D-Cache
 - Prevents pollution by vectors & tensors
- Larger L2 acts as an L1 for vectors
 - In addition to backing I-Cache & D-Cache
 - Software prefetch hides DDR latency
- TCM for vectors & tensors:
 - Acts as a software-managed cache
 - More scalable than a hardware cache
 - Much higher bandwidth than a typical cache
 - Enables very high-bandwidth scatter/gather
 - Predictable performance no misses
 - Virtually addressed DMA for hiding DDR latency



Efficiency

Tensor Data Locality – Temporal and Spatial

- Data locality is key to tensor compute efficiency
- N:1 compute:memory matrix multiply
 - $2N^2$ data read and transferred
 - For 2N³ compute
 - Single biggest reason for a dedicated tensor or matrix engine
- Output stationary:
 - Accumulators are wider bit-width than input activations & weights
 - Accumulate across all input channels and filter taps
- Convolution activations reuse:
 - Input activations with halo read once for each hardware output tensor
 - Convolution as a sequence of unaligned matrix multiplies
- Hardware SIMD tensor contiguous in memory
 - Maximized memory bandwidth, just like a SIMD vector is contiguous
 - Responsibility of software to organize data in these chunks





Floating-Point vs. Fixed-Point

- With tensor hardware, raw computational area & energy dominates, making compute efficiency paramount
- With Normal data, precision yields accuracy, not exponent
 - Beyond 2-bit exponent only harms accuracy with optimal SNR scaling
 - Simple int/fixed-point yields lowest cost for any accuracy
- Floating point vs. fixed point (FXP) accumulation increases overhead
 - Fixed-point or Kulisch accumulation best for small exponents widths: exact and lower cost
- DNNs typically have Normal data, but not always
 - Floating point vs. fixed point studied in (van Baalen et al., 2023)
 - CNNs relatively Normal INT8 outperforming FP8 with Post Training Quantization (PTQ) and Quantization Aware Training (QAT)
 - Transformers have outliers due to softmax <u>(Bondarenko et al, 2023)</u>, but QAT naturally pulls in the outliers
- Large fixed-point capacity + floating-point
 - Fixed-point: A16W16, A16W8, A8W8, A8W4
 - Floating-point: FP16*FP16



| Model | FP32 | INT8 PTQ | FP8E4 PTQ | A8W4 QAT | INT8 QAT | FP8E4 QAT |
|-------------|--------|----------|-----------|----------|----------|-----------|
| ResNet18 | 69.72% | -0.08% | -1.15% | 0.29% | 0.71% | -0.37% |
| MobileNetV2 | 71.70% | -0.76% | -5.65% | -0.53% | 0.12% | -0.81% |
| HRNet | 81.05% | -0.12% | -0.28% | | 0.22% | 0.01% |
| DeeplabV3 | 72.91% | -1.67% | -34.98% | 0.10% | 1.08% | 0.31% |
| SalsaNext | 55.80% | -1.58% | -0.68% | | -0.80% | -0.60% |
| BERT(GLUE) | 83.06% | -12.03% | -0.26% | -0.42% | 0.20% | 0.85% |

Performance & Energy vs. Bits

- Lower bit widths affect accuracy, but improve many other dimensions:
 - Memory footprint/bandwidth/energy TCM & DDR, activations & weights
 - Compute bandwidth/energy
- Can scale *quadratically* vs. bit width:
 - For matrix/convolution dominated workloads
 - Linear scaling with bit width of each operand
 - Smaller widths fit better into memory (more locality)
- Multiple PTQ & QAT techniques are used to maximize accuracy with reduced bits



Pruning vs. Quantization

- At the cost of accuracy, pruning weights:
 - Enables a smaller [compressed] model
 - Reduces compute energy with more zeros
 - Allows for skipping compute for each zero
 - But, costly (area/energy) for dense case in tensor architecture
- Quantization also costs accuracy with similar [potential] benefits
 - Zero specific lower bits rather than random elements
- Comparison from (Kuzmin et al., 2023) shown:
 - Quantization consistently better for given compressed/packed model bits
- Focus on deep quantization rather than deep pruning
 - But pruned/compressed models are supported



Application

Target Industries

- Single architecture across a wide range of platforms
- Specific implementations with different configurations are used across industries
- Maximized energy-efficient single-core performance and multi-core when needed
- Typically, multiple concurrent uses on any given platform, including with single-core
- Programmability is key to adapting to new demands



Performance



Al-Benchmark Mobile (int8)

Leading edge performance with 50% to >100% year-over-year gains

References

Mart van Baalen, Andrey Kuzmin, Suparna S Nair, Yuwei Ren, Eric Mahurin, Chirag Patel, Sundar Subramanian, Sanghyuk Lee, Markus Nagel, Joseph Soriaga, Tijmen Blankevoort. (2023). "FP8 versus INT8 for efficient deep learning inference", <u>https://arxiv.org/abs/2303.17951</u>

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Andrey Kuzmin, Markus Nagel, Mart van Baalen, Arash Behboodi, Tijmen Blankevoort. (2023). "Pruning vs Quantization: Which is Better?", <u>https://arxiv.org/abs/2307.02973</u>

Thank you

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